Parallel Computer Architectures

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- □ Flynn's Taxonomy
- Classification of Parallel Computers Based on Architectures

Flynn's Taxonomy

- Based on notions of instruction and data streams
 - SISD (Single Instruction stream, a Single Data stream)
 - SIMD (Single Instruction stream, Multiple Data streams)
 - MISD (Multiple Instruction streams, a Single Data stream)
 - MIMD (Multiple Instruction streams, Multiple Data stream)
- Popularity
 - MIMD > SIMD > MISD



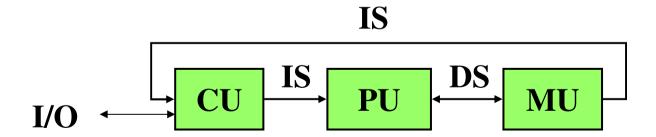
□ SISD

Conventional sequential machines

IS: Instruction Stream DS: Data Stream

CU: Control Unit **PU**: Processing Unit

MU: Memory Unit

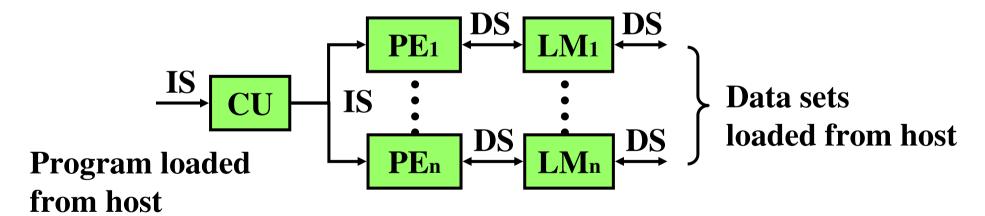




□ SIMD

- Vector computers, processor arrays
- Special purpose computations

PE: Processing Element LM: Local Memory

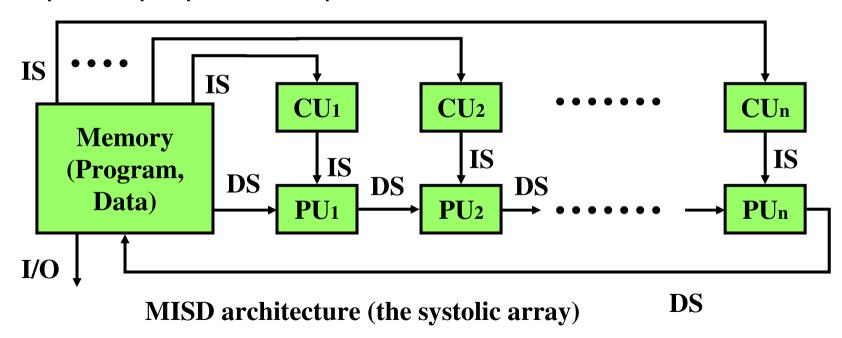


SIMD architecture with distributed memory



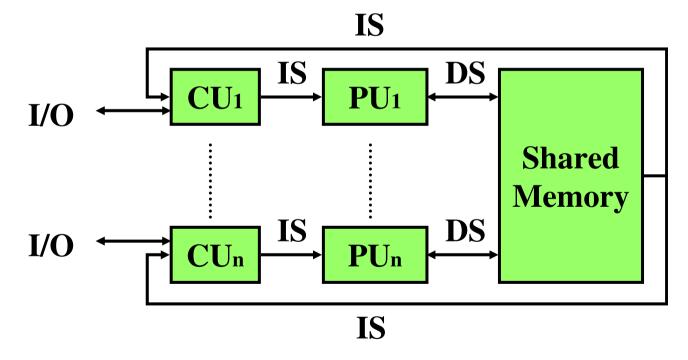
□ MISD

- Systolic arrays
- Special purpose computations





General purpose parallel computers



MIMD architecture with shared memory



- □ Pipelined Computers
- □ Dataflow Architectures
- Data Parallel Systems
- Multiprocessors
- Multicomputers



Pipeline Computers (1)

- □ Instructions are divided into a number of steps (segments, stages)
- □ At the same time, several instructions can be loaded in the machine and be executed in different steps



Pipeline Computers (2)

- IF instruction fetch
- ID instruction decode and register fetch
- EX- execution and effective address calculation
- MEM memory access
- WB- write back

-									<u> </u>
Instruction #	1	2	3	4	5	6	7	8	9
Instruction i	IF	ID	EX	MEM	WB				
Instruction i+1		IF	ID	EX	MEM	WB		_	
Instruction i+2			IF	ID	EX	MEM	WB		
Instruction i+3				IF	ID	EX	MEM	WB	
Instruction i+4					IF	ID	EX	MEM	WB

Cycles



Data-driven model

- A program is represented as a directed acyclic graph in which a node represents an instruction and an edge represents the data dependency relationship between the connected nodes
- Firing rule
 - » A node can be scheduled for execution if and only if its input data become valid for consumption
- Dataflow languages
 - Id, SISAL, Silage, LISP,...
 - Single assignment, applicative(functional) language
 - Explicit parallelism

$$z = (a + b) * c$$

$$b$$

$$c$$

$$c$$

The dataflow representation of an arithmetic expression

Dataflow Computer

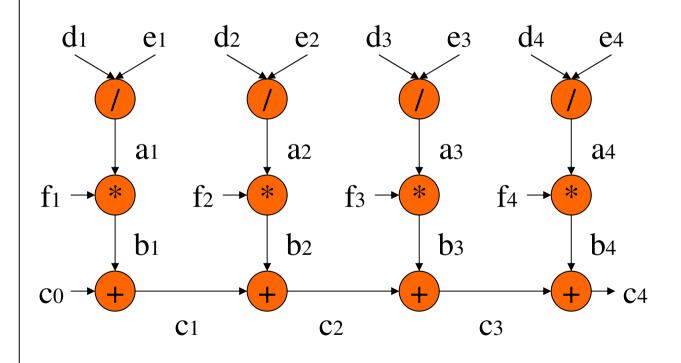
- Execution of instructions is driven by data availability
 - What is the difference between this and normal (control flow) computers?
- Advantages
 - Very high potential for parallelism
 - High throughput
 - Free from side-effect
- Disadvantages
 - Time lost waiting for unneeded arguments
 - High control overhead
 - Difficult in manipulating data structures



Dataflow Representation

```
input d,e,f
   c_0 = 0
for i from 1 to 4
do
   begin
      a_i := d_i / e_i
      b_i := a_i * f_i
      c_i := b_i + c_{i-1}
   end
```

output a, b, c



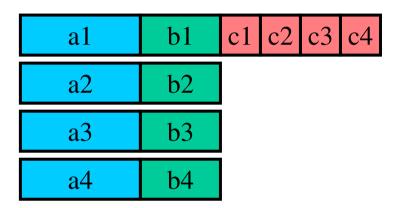
Assume all the external inputs are available before entering do loop +: 1 cycle, *: 2 cycles, /: 3 cycles,



Sequential execution on a uniprocessor in 24 cycles

How long will it take to execute this program on a dataflow computer with 4 processors?





Data-driven execution on a 4-processor dataflow computer in 9 cycles

Can we further reduce the execution time of this program?



Data Parallel Systems (1)

Programming model

- Operations performed in parallel on each element of data structure
- Logically single thread of control, performs sequential or parallel steps
- Conceptually, a processor associated with each data element



Data Parallel Systems (2)

SIMD Architectural model

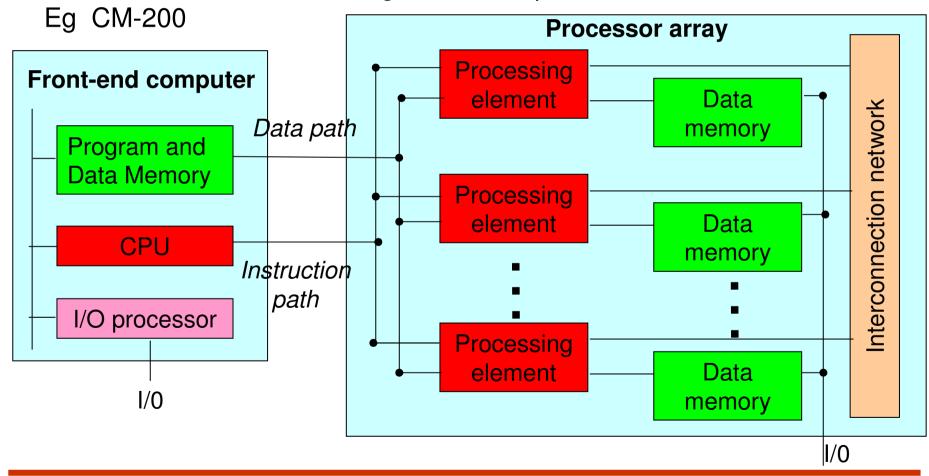
- Array of many simple, cheap processors with little memory each
 - » Processors don't sequence through instructions
- Attached to a control processor that issues instructions
- Specialized and general communication, cheap global synchronization



- Instruction set includes operations on vectors as well as scalars
- □ 2 types of vector computers
 - Processor arrays
 - Pipelined vector processors

Processor Array

□ A sequential computer connected with a set of identical processing elements simultaneouls doing the same operation on different data.





Pipeline Vector Processor

- □ Stream vector from memory to the CPU
- □ Use pipelined arithmetic units to manipulate data
- □ Eg: Cray-1, Cyber-205



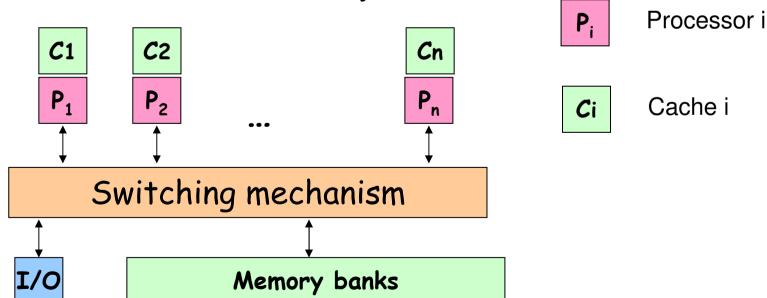


- Consists of many fully programmable processors each capable of executing its own program
- Shared address space architecture
- Classified into 2 types
 - Uniform Memory Access (UMA) Multiprocessors
 - Non-Uniform Memory Access (NUMA)
 Multiprocessors



UMA Multiprocessor (1)

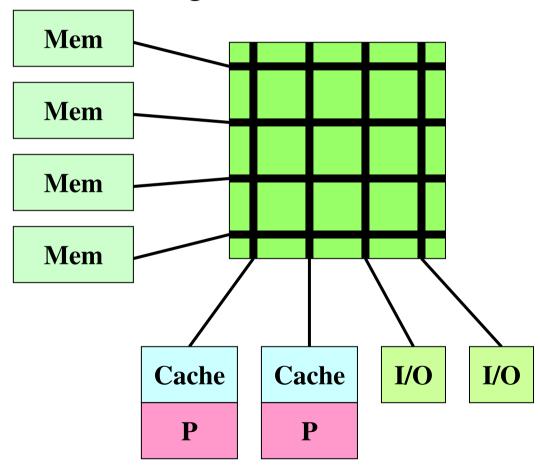
- Uses a central switching mechanism to reach a centralized shared memory
- All processors have equal access time to global memory
- Tightly coupled system
- □ Problem: cache consistency





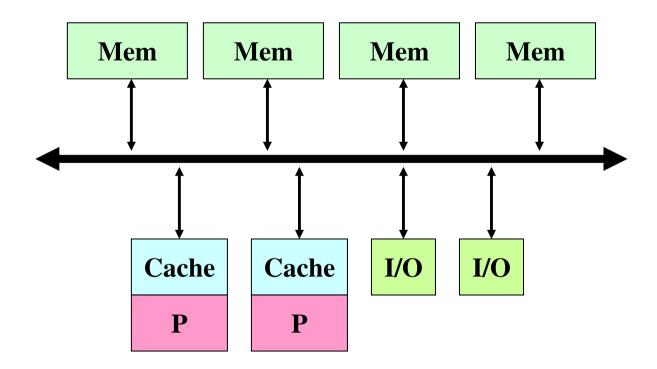
UMA Multiprocessor (2)

Crossbar switching mechanism



UMA Multiprocessor (3)

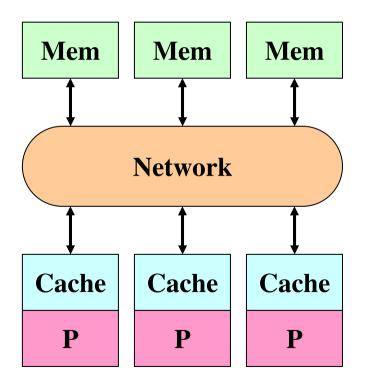
Shared-bus switching mechanism





UMA Multiprocessor (4)

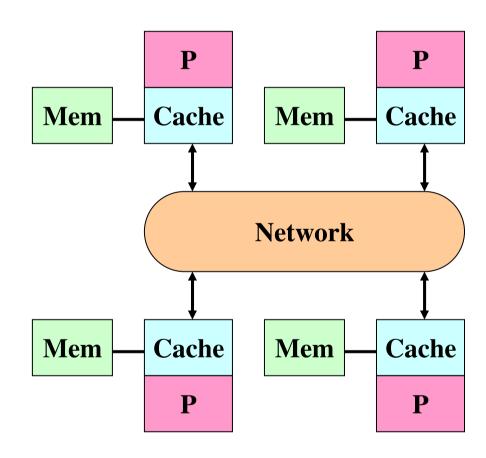
□ Packet-switched network





NUMA Multiprocessor

- Distributed shared memory combined by local memory of all processors
- Memory access time depends on whether it is local to the processor
- Caching shared (particularly nonlocal) data?



Distributed Memory



Current Types of Multiprocessors

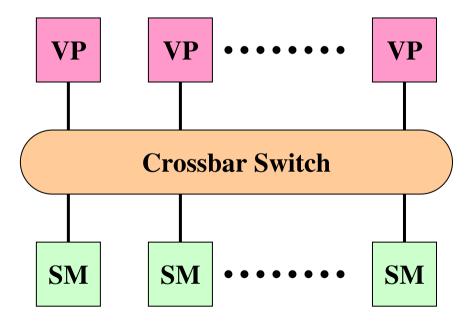
- □ PVP (Parallel Vector Processor)
 - A small number of proprietary vector processors connected by a high-bandwidth crossbar switch
- □ SMP (Symmetric Multiprocessor)
 - A small number of COST microprocessors connected by a high-speed bus or crossbar switch
- □ DSM (Distributed Shared Memory)
 - Similar to SMP
 - The memory is physically distributed among nodes.



PVP (Parallel Vector Processor)

VP: Vector Processor

SM: Shared Memory

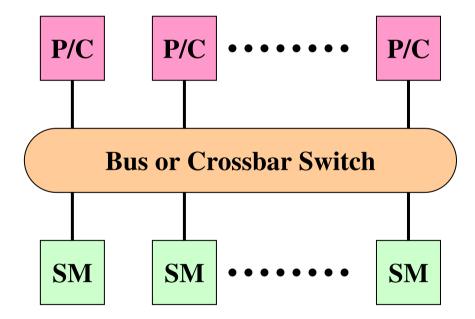




SMP (Symmetric Multi-Processor)

P/C: Microprocessor and Cache

SM: Shared Memory





DSM (Distributed Shared Memory)

MB: Memory Bus

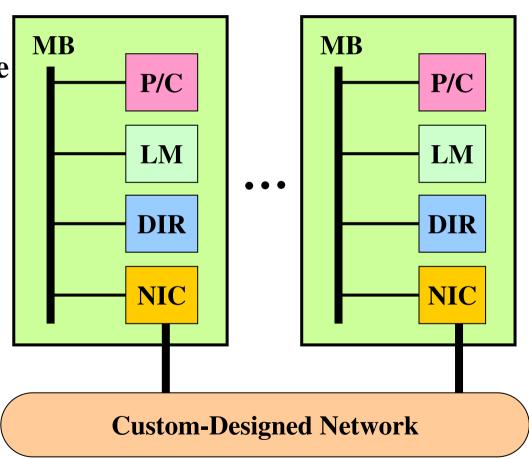
P/C: Microprocessor & Cache

LM: Local Memory

DIR: Cache Directory

NIC: Network Interface

Circuitry

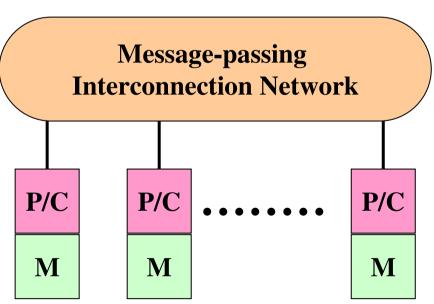




- Consists of many processors with their own memory
- No shared memory
- □ Processors interact via message passing → loosely coupled system

P/C: Microprocessor & Cache

M: Memory





Current Types of Multicomputers

- MPP (Massively Parallel Processing)
 - Total number of processors > 1000
- Cluster
 - Each node in system has less than 16 processors.
- Constellation
 - Each node in system has more than 16 processors

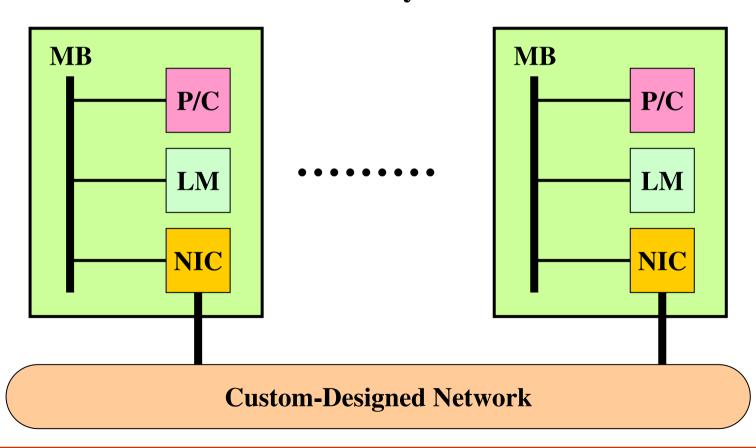


P/C: Microprocessor & Cache

NIC: Network Interface Circuitry

MB: Memory Bus

LM: Local Memory





MB: Memory Bus

P/C: Microprocessor &

Cache

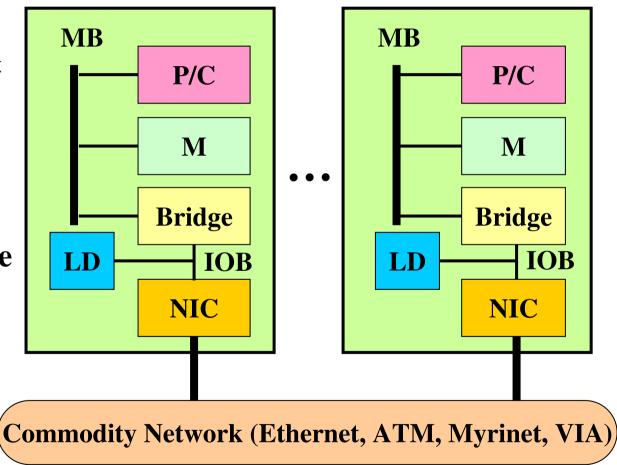
M: Memory

LD: Local Disk

IOB: I/O Bus

NIC: Network Interface

Circuitry





P/C: Microprocessor & Cache

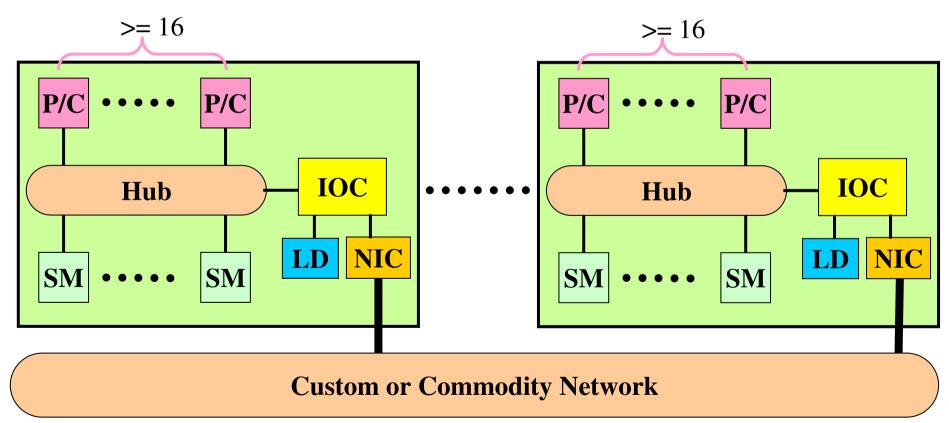
NIC: Network Interface Circuitry

IOC: I/O Controller

MB: Memory Bus

SM: Shared Memory

LD: Local Disk





Trend in Parallel Computer Architectures

