Parallel Paradigms & Programming Models

Thoai Nam



- Parallel programming paradigms
- □ Programmability Issues
- □ Parallel programming models
 - Implicit parallelism
 - Explicit parallel models
 - Other programming models

ВК

Parallel Programming Paradigms

- Parallel programming paradigms/models are the ways to
 - Design a parallel program
 - Structure the algorithm of a parallel program
 - Deploy/run the program on a parallel computer system
- Commonly-used algorithmic paradigms
 - Phase parallel
 - Synchronous and asynchronous iteration
 - Divide and conquer
 - Pipeline
 - Process farm
 - Work pool

Parallel Programmability Issues

- The programmability of a parallel programming models is
 - How much easy to use this system for developing and deploying parallel programs
 - How much the system supports for various parallel algorithmic paradigms
- Programmability is the combination of
 - Structuredness
 - Generality
 - Portability



- □ A program is *structured* if it is comprised of *structured constructs* each of which has these 3 properties
 - Is a single-entry, single-exit construct
 - Different semantic entities are clearly identified
 - Related operations are enclosed in one construct
- □ The structuredness mostly depends on
 - The programming language
 - The design of the program



- □ A program class C is as general as or more general than program class D if:
 - For any program Q in D, we can write a program P in C
 - Both P & Q have the same semantics
 - P performs as well as or better than Q



- A program is portable across a set of computer system if it can be transferred from one machine to another with little effort
- Portability largely depends on
 - The language of the program
 - The target machine's architecture
- Levels of portability
 - 1. Users must change the program's algorithm
 - 2. Only have to change the source code
 - 3. Only have to recompile and relink the program
 - 4. Can use the executable directly



Parallel Programming Models

- Widely-accepted programming models are
 - Implicit parallelism
 - Data-parallel model
 - Message-passing model
 - Shared-variable model (Shared Address Space model)

Implicit Parallelism

- □ The compiler and the run-time support system automatically exploit the parallelism from the sequential-like program written by users
- Ways to implement implicit parallelism
 - Parallelizing Compilers
 - User directions
 - Run-time parallelization



- □ A parallelizing (restructuring) compiler must
 - Performs dependence analysis on a sequential program's source code
 - Uses transformation techniques to convert sequential code into native parallel code
- □ Dependence analysis is the identifying of
 - Data dependence
 - Control dependence



Parallelizing Compiler(cont'd)

□ Data dependence

$$\begin{array}{ccccc} X & = & X & + & 1 \\ Y & = & X & + & Y \end{array}$$

□ Control dependence

If
$$f(X) = 1$$
 then $Y = Y + Z$;

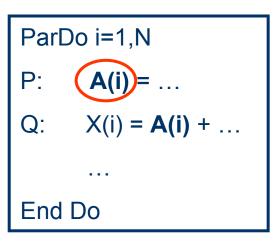
- When dependencies do exist, transformation techniques/ optimizing techniques should be used
 - To eliminate those dependencies or
 - To make the code parallelizable, if possible



Some Optimizing Techniques for Eliminating Data Dependencies

Privatization technique

Q needs the value **A** of P, so N iterations of the Do loop can not be parallelized



Each iteration of the Do loop have a private copy **A(i)**, so we can execute the Do loop in parallel



Some Optimizing Techniques for Eliminating Data Dependencies(cont'd)

□ Reduction technique

Do i=1,N

P: X(i) = ...

Q: Sum = Sum + X(i)

. . .

End Do

The Do loop can not be executed in parallel since the computing of Sum in the i-th iteration needs the values of the previous iteration

ParDo i=1,N

P: X(i) = ...

Q: Sum = sum_reduce(X(i))

...

End Do

A parallel reduction function is used to avoid data dependency



- Users help the compiler in parallelizing by
 - Providing additional information to guide the parallelization process
 - Inserting compiler directives (pragmas) in the source code
- User is responsible for ensuring that the code is correct after parallelization
- □ Example (Convex Exemplar C)



- Parallelization involves both the compiler and the run-time system
 - Additional construct is used to decompose the sequential program into multiple tasks and to specify how each task will access data
 - The compiler and the run-time system recognize and exploit parallelism at both the compile time and run-time
- □ Example: Jade language (Stanford Univ.)
 - More parallelism can be recognized
 - Automatically exploit the irregular and dynamic parallelism



- Advantages of the implicit programming model
 - Ease of use for users (programmers)
 - Reusability of old-code and legacy sequential applications
 - Faster application development time
- Disadvantages
 - The implementation of the underlying run-time systems and parallelizing compilers is so complicated and requires a lot of research and studies
 - Research outcome shows that automatic parallelization is not so efficient (from 4% to 38% of parallel code written by experienced programmers)



Explicit Programming Models

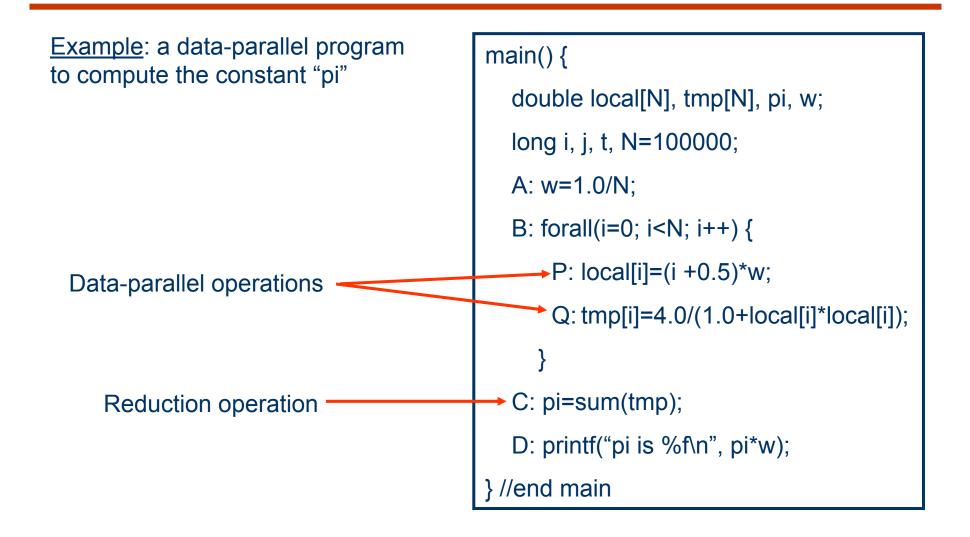
- □ Data-Parallel
- Message-Passing
- □ Shared-Variable



- □ Applies to either SIMD or SPMD modes
- □ The same instruction or program segment executes over different data sets simultaneously
- Massive parallelism is exploited at data set level
- Has a single thread of control
- □ Has a global naming space
- Applies loosely synchronous operation



Data-Parallel: An Example





Message-Passing Model

- Multithreading: program consists of multiple processes
 - Each process has its own thread of control
 - Both control parallelism (MPMD) and data parallelism (SPMD) are supported
- □ Asynchronous Parallelism
 - All process execute asynchronously
 - Must use special operation to synchronize processes
- □ Multiple Address Spaces
 - Data variables in one process is invisible to the others
 - Processes interact by sending/receiving messages



Explicit Interactions

 Programmer must resolve all the interaction issues: data mapping, communication, synchronization and aggregation

□ Explicit Allocation

 Both workload and data are explicitly allocated to the process by the user



Message-Passing Model: An Example

Example: a message-passing program to compute the constant "pi"

```
#define N 1000000
                             main() {
                               double local, pi, w;
                               long i, taskid, numtask;
                            A: w=1.0/N:
                               MPI Init(&argc, &argv);
                                MPI Comm rank(MPI COMM WORLD, &taskid);
                               MPI_Comm_size(MPI_COMM_WORLD, &numtask);
Message-Passing
                             B: for (i=taskid;i<N;i=i+numtask) {
      operations
                                      local= (i + 0.5)*w:
                                      local=4.0/(1.0+local*local); }
                             C: MPI_Reduce(&local, &pi, 1, MPI_DOUBLE,
                                             MPI SUM, 0, MPI COMM WORLD);
                             if (taskid==0) printf("pi is %f\n", pi*w);
                                 MPI_Finalize();
                             } //end main
```



- □ Has a single address space
- Has multithreading and asynchronous model
- Data reside in a single, shared address space, thus does not have to be explicitly allocated
- Workload can be implicitly or explicitly allocated
- Communication is done implicitly
 - Through reading and writing shared variables
- □ Synchronization is explicit



Shared-Variable Model: An Example

```
#define N 1000000
main() {
   double local, pi=0.0, w;
   long i;
A: w=1.0/N;
B: #pragma parallel
   #pragma shared (pi,w)
   #pragma local(i,local)
          #pragma pfor iterate (i=0;N;1)
          for(i=0;i< N;i++){}
                local= (i + 0.5)*w;
                local=4.0/(1.0+local*local);
          #pragma critical
                pi=pi+local;
D: if (taskid==0) printf("pi is %f\n", pi*w);
} //end main
```



Comparision of Four Models

| Issues | Implicit | Data-parallel | Message-passing | Shared-Variable |
|-------------------------------|------------|---------------------------|------------------------|----------------------------|
| Platform-independent examples | Kap, Forge | Fortran 90, HPF, HPC++ | PVM, MPI | X3H5 |
| Platform-dependent examples | | CM C* | SP2 MPL, Paragon Nx | Cray Craft, SGI Power C |
| Parallelism issues | * * * * | * * * | * | * * |
| Allocation issues | * * * * | ** | * | * * * |
| Communication | * * * * | * * * | * | * * * |
| Synchronization | * * * * | *** | * * | * |
| Aggregation | * * * * | *** | *** | * |
| Irregularity | * * * * | * * | * * | * * * |
| Termination | * * * * | * * * * | * * | * |
| Determinacy | * * * * | *** | * * | * |
| Correctness | * * * * | * * * | * * | * |
| Generality | * | * * | * * * | * * * |
| Portability | * * * * | * * * | * * | * |
| Structuredness | * * * * | * * | * | * |



Comparision of Four Models (cont'd)

- Implicit parallelism
 - Easy to use
 - Can reuse existing sequential programs
 - Programs are portable among different architectures
- □ Data parallelism
 - Programs are always determine and free of deadlocks/livelocks
 - Difficult to realize some loosely sync. program



Comparision of Four Models (cont'd)

Message-passing model

- More flexible than the data-parallel model
- Lacks support for the work pool paradigm and applications that need to manage a global data structure
- Be widely-accepted
- Expoit large-grain parallelism and can be executed on machines with native shared-variable model (multiprocessors: DSMs, PVPs, SMPs)

□ Shared-variable model

- No widely-accepted standard → programs have low portability
- Programs are more difficult to debug than message-passing programs



Other Programming Models

- Functional programming
- Logic programming
- Computing-by-learning
- Object-oriented programming